

8-Bit Microprocessing Unit

The MC6809 is a high-performance 8-bit microprocessor which supports modern programming techniques such as position independence, re-entrancy, and modular programming.

This third-generation addition to the M6800 Family has major architectural improvements which include additional registers, instructions, and addressing modes.

The basic instructions of any computer are greatly enhanced by the presence of powerful addressing modes. The MC6809 has the most complete set of addressing modes available on any 8bit microprocessor.

The MC6809 has hardware and software features which make it an ideal processor for higher level language execution or standard controller applications.

MC6800 COMPATIBLE

- · Hardware Interfaces with All M6800 Peripherals
- Software Upward Source Code Compatible Instruction Set and Addressing Modes

ARCHITECTURAL FEATURES

- · Two 16-Bit Index Registers
	- . Two 16-Bit Indexable Stack Pointers
	- Two 8-Bit Accumulators Can Be Concatenated To Form One 16-Bit Accumulator
- Direct Page Register Allows Direct Addressing Throughout Memory

HARDWARE FEATURES

- On-Chip Oscillator (Crystal Frequency = $4 \times E$)
- DMA BREQ Allows DMA Operation on Memory Refresh
- Fast Interrupt Request Input Stacks Only Condition Code Register and Program Counter
- MRDY Input Extends Data Access Times for Use with Slow Memory
- Interrupt Acknowledge Output Allows Vectoring by Devices
- Sync Acknowledge Output Allows for Synchronization to External Event
- Single Bus-Cycle RESET
- Single 5-Volt Supply Operation
- . NMI Inhibited After RESET Until After First Load of Stack Pointer
- **Early Address Valid Allows Use with Slower Memories**
- **.** Early Write Data for Dynamic Memories

SOFTWARE FEATURES

- 10 Addressing Modes
	- 6800 Upward Compatible Addressing Modes
	- Direct Addressing Anywhere in Memory Map
	- Long Relative Branches
	- Program Counter Relative
	- True Indirect Addressing
	- Expanded Indexed Addressing:
	- 0-, 5-, 8-, or 16-Bit Constant Offsets
		- 8- or 16-Bit Accumulator Offsets
		- Auto Increment Decrement by 1 or 2
- Improved Stack Manipulation
- · 1464 Instructions with Unique Addressing Modes
- \bullet 8 × 8 Unsigned Multiply
- 16-Bit Arithmetic
- Transfer/Exchange All Registers
- . Push Pull Any Registers or Any Set of Registers
- Load Effective Address

This document contains information on a new product. Specifications and information herein are subject to change without notice.

MOTOROLA MICROPROCESSOR DATA

3-1363

MAXIMUM RATINGS

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage levels (e.g., either Vss or Vccl.

THERMAL CHARACTERISTICS

POWER CONSIDERATIONS

The average chip-junction temperature, $T_{\rm Jt}$ in $^{\circ}$ C can be obtained from:

$$
\mathsf{T}_{\mathsf{J}} = \mathsf{T}_{\mathsf{A}} + (\mathsf{P}_{\mathsf{D}} \cdot \mathsf{H}_{\mathsf{J} \mathsf{A}})
$$

 (1)

where:

= Ambient Temperature, $^{\circ}$ C

 T_{A} θ JA = Package Thermal Resistance, Junction-to-Ambient, C W

 $\tilde{P_{D}}$

PINT

 $= P_{INT} + P_{PORT}$
= $P_{C} \times V_{CC}$, Watts — Chip Internal Power
= Port Power Dissipation, Watts — User Determined PPORT

For most applications $P_{PORT} < P_{INT}$ and can be neglected. PpORT may become significant if the device is configured to drive Darlington bases or sink LED loads. An approximate relationship betwee

$$
n \, P_D \text{ and } T_J \text{ (if } P_{\text{PORT}} \text{ is neglected)} \text{ is:}
$$

$$
P_D = K \div (T_J + 273^{\circ}C)
$$

Solving equations (1) and (2) for K gives:

$$
K = P_D \cdot (T_A + 273 \cdot C) + \theta J A \cdot P D^2
$$

where K is a constant pertaining to the particular part. K can be determined from equation (3) by measuring P_D (at equilibrium) for a known T_A . Using this value of K, the values of P_D and T_J can be obtained by solving equations (1) and (2) iteratively for any value of T_A .

ELECTRICAL CHARACTERISTICS (V_{CC} = 5.0 V ± 5%, V_{SS} = 0, T_A = T_L to T_H unless otherwise noted)

 * Capacitances are periodically tested rather than 100% tested.

MOTOROLA MICROPROCESSOR DATA

3-1364

FIGURE 1 - BUS TIMING

Unit μS

 ns

 ns

 $\overline{\mathsf{ns}}$

 ns ns

> \overline{a} ns ns \overline{ns}

 $\overline{\mathsf{ns}}$ ns ns ns ms

 ns

* Address and data hold times are periodically tested rather than 100% tested

NOTES:

- 1. Voltage levels shown are V_L \approx 0.4 V, V_H \approx 2.4 V, unless otherwise specified.
2. Measurement points shown are 0.8 V and 2.0 V, unless otherwise specified.
-
- 3. Usable access time is computed by: $1 4 7$ max $+ 10 17$.
-
-
- 4. Hold time $\frac{1}{2}$ (c) for BA and BS is not specified.
5. Maximum t_{cyc} during MRDY or DMA BREQ is 16 μ s.
6. MC6809 1.0 MHz, MC68A09 1.5 MHz, MC68B09 2.0 MHz.

MOTOROLA MICROPROCESSOR DATA

FIGURE 2 - MC6809 EXPANDED BLOCK DIAGRAM

PROGRAMMING MODEL

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As shown in Figure 4, the MC6809 adds three registers to the set available in the MC6800. The added registers include a direct page register, the user stack pointer, and a second index register.

ACCUMULATORS (A, B, D)

The A and B registers are general purpose accumulators which are used for arithmetic calculations and manipulation of data.

Certain instructions concatenate the A and B registers to form a single 16-bit accumulator. This is referred to as the D register, and is formed with the A register as the most significant byte.

DIRECT PAGE REGISTER (DP)

The direct page register of the MC6809 serves to enhance the direct addressing mode. The content of this register appears at the higher address outputs (A8-A15) during direct addressing instruction execution. This allows the direct mode to be used at any place in memory, under program control. To ensure M6800 compatibility, all bits of this register are cleared during processor reset.

MOTOROLA MICROPROCESSOR DATA

3-1366

FIGURE 4 - PROGRAMMING MODEL OF THE MICROPROCESSING UNIT

INDEX REGISTERS (X, Y)

The index registers are used in indexed mode of addressing. The 16-bit address in this register takes part in the calculation of effective addresses. This address may be used to point to data directly or may be modified by an optional constant or register offset. During some indexed modes, the contents of the index register are incremented or decremented to point to the next item of tabular type data. All four pointer registers (X, Y, U, S) may be used as index registers.

STACK POINTER (U,S)

The hardware stack pointer (S) is used automatically by the processor during subroutine calls and interrupts. The stack pointers of the MC6809 point to the top of the stack, in contrast to the MC6800 stack pointer, which pointed to the next free location on the stack. The user stack pointer (U) is controlled exclusively by the programmer. This allows arguments to be passed to and from subroutines with ease. Both stack pointers have the same indexed mode addressing capabilities as the X and Y registers, but also support Push and Pull instructions. This allows the MC6809 to be used efficiently as a stack processor, greatly enhancing its ability to support higher level languages and modular programming.

PROGRAM COUNTER

The program counter is used by the processor to point to the address of the next instruction to be executed by the processor. Relative addressing is provided allowing the program counter to be used like an index register in some situations.

CONDITION CODE REGISTER

The condition code register defines the state of the processor at any given time. See Figure 5.

FIGURE 5 - CONDITION CODE REGISTER FORMAT

CONDITION CODE REGISTER DESCRIPTION

CARRY FLAG (C)

Bit 0 is the carry flag, and is usually the carry from the binary ALU. C is also used to represent a 'borrow' from subtract-like instructions (CMP, NEG, SUB, SBC) and is the complement of the carry from the binary ALU.

OVERFLOW FLAG (V)

Bit 1 is the overflow flag, and is set to a one by an operation which causes a signed twos complement arithmetic overflow. This overflow is detected in an operation in which the carry from the MSB in the ALU does not match the carry from the MSB-1.

ZERO FLAG (Z)

Bit 2 is the zero flag, and is set to a one if the result of the previous operation was identically zero.

MOTOROLA MICROPROCESSOR DATA

3-1367

NEGATIVE ELAG (N)

Bit 3 is the negative flag, which contains exactly the value of the MSB of the result of the preceding operation. Thus, a negative twos-complement result will leave N set to a one.

IRQ MASK (I)

Bit 4 is the IRO mask bit. The processor will not recognize interrupts from the IRO line if this bit is set to a one. NMI, FIRO, IRO, RESET, and SWI all set I to a one. SWI2 and SWI3 do not affect I.

HALF CARRY (H)

Bit 5 is the half-carry bit, and is used to indicate a carry from bit 3 in the ALU as a result of an 8-bit addition only (ADC or ADD). This bit is used by the DAA instruction to perform a BCD decimal add adjust operation. The state of this flag is undefined in all subtract-like instructions.

FIRQ MASK (F)

Bit 6 is the FIRQ mask bit. The processor will not recognize interrupts from the FIRO line if this bit is a one. NMI, FIRQ, SWI, and RESET all set F to a one. IRQ, SWI2, and SWI3 do not affect F

ENTIRE FLAG (E)

Bit 7 is the entire flag, and when set to a one indicates that the complete machine state (all the registers) was stacked, as opposed to the subset state (PC and CC). The E bit of the stacked CC is used on a return from interrupt (RTI) to determine the extent of the unstacking. Therefore, the current E left in the condition code register represents past action.

PIN DESCRIPTIONS

POWER (VSS, VCC)

Two pins are used to supply power to the part: VSS is ground or 0 volts, while V_{CC} is +5.0 V \pm 5%.

ADDRESS BUS (A0-A15)

Sixteen pins are used to output address information from the MPU onto the address bus. When the processor does not require the bus for a data transfer, it will output address FFFF₁₆, R/ \overline{W} = 1, and BS = 0; this is a "dummy access" or VMA cycle. Addresses are valid on the rising edge of Q. All address bus drivers are made high impedance when output bus available (BA) is high. Each pin will drive one Schottky TTL load or four LSTTL loads, and 90 pF.

DATA BUS (D0-D7)

These eight pins provide communication with the system bidirectional data bus. Each pin will drive one Schottky TTL load or four LSTTL loads, and 130 pF.

READ/WRITE (R/W)

This signal indicates the direction of data transfer on the data bus. A low indicates that the MPU is writing data onto the data bus. R/\overline{W} is made high impedance when BA is high. R/\overline{W} is valid on the rising edge of Q.

RESET

A low level on this Schmitt-trigger input for greater than one bus cycle will reset the MPU, as shown in Figure 6. The reset vectors are fetched from locations FFFE₁₆ and FFFF₁₆ (Table 1) when interrpt acknowledge is true, (BA.BS - 1). During initial power on, the RESET line should be held low until the clock oscillator is fully operational. See Figure 7.

Because the RESET pin has a Schmitt-trigger input with a threshold voltage higher than that of standard peripherals, a simple R C network may be used to reset the entire system. This higher threshold voltage ensures that all peripherals are out of the reset state before the processor.

HALT

A low level on this input pin will cause the MPU to stop running at the end of the present instruction and remain halted indefinitely without loss of data. When halted, the BA output is driven high indicating the buses are high impedance. BS is also high which indicates the processor is in the halt or bus grant state. While halted, the MPU will not respond to external real-time requests (FIRQ, IRQ) although DMA BREQ will always be accepted, and NMI or RESET will be latched for later response. During the halt state, Q and E continue to run normally. If the MPU is not runnig, (RESET, DMA BREQ), a halted state (BAOBS = 1) can be achieved by pulling HALT low while RESET is still low. If DMA BREQ and HALT are both pulled low, the processor will reach the last cycle of the instruction (by reverse cycle stealing) where the machine will then become halted. See Figure 8.

BUS AVAILABLE, BUS STATUS (BA, BS)

The bus available output is an indication of an internal control signal which makes the MOS buses of the MPU high impedance. This signal does not imply that the bus will be available for more than one cycle. When BA goes low, a dead cycle will elapse before the MPU acquires the bus

The bus status output signal, when decoded with BA, represents the MPU state (valid with leading edge of Q).

MOTOROLA MICROPROCESSOR DATA

3-1368

MOTOROLA MICROPROCESSOR DATA

3-1369

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MC6809

FIGURE 7 - CRYSTAL CONNECTIONS AND OSCILLATOR START UP

NOTE: Waveform measurements for all inputs and outputs are specified at logic high 2.0 V and logic low 0.8 V unless otherwise specified.

NOTE: These are representative AT-cut crystal parameters only. Crystals of other types of cut may also be used.

MOTOROLA MICROPROCESSOR DATA 3-1370

FIGURE 8 - HALT AND SINGLE INSTRUCTION **EXECUTION FOR SYSTEM DEBUG**

NOTE: Waveform measurements for all inputs and outputs are specified at logic high 2.0 V and logic low 0.8 V unless otherwise specified.

INTERRUPT ACKNOWLEDGE is indicated during both cycles of a hardware-vector-fetch (RESET, NMI, FIRO, IRO, SWI, SWI2, SWI3). This signal, plus decoding of the lower four address lines, can provide the user with an indication of which interrupt level is being serviced and allow vectoring by device. See Table 1.

SYNC ACKNOWLEDGE is indicated while the MPU is waiting for external synchronization on an interrupt line.

HALT/BUS GRANT is true when the MC6809 is in a halt or bus grant condition.

TABLE 1 - MEMORY MAP FOR INTERRUPT VECTORS

NON MASKABLE INTERRUPT (NMI)*

A negative transition on this input requests that a nonmaskable interrupt sequence be generated. A non-maskable interrupt cannot be inhibited by the program. It also has a higher priority than FIRQ, IRQ, or software interrupts. During recognition of an NMI, the entire machine state is saved on the hardware stack. After reset, an NMI will not be recognized until the first program load of the hardware stack pointer (S). The pulse width of NMI low must be at least one E cycle. If the $\overline{\text{NMI}}$ input does not meet the minimum set up with respect to Q, the interrupt will not be recognized until the next cycle. See Figure 9.

FAST-INTERRUPT REQUEST (FIRO)*

A low level on this input pin will initiate a fast interrupt sequence, provided its mask bit (F) in the CC is clear. This sequence has priority over the standard interrupt request (IRO), and is fast in the sense that it stacks only the contents of the condition code register and the program counter. The interrupt service routine should clear the source of the interrupt before doing an RTI. See Figure 10.

INTERRUPT REQUEST (IRQ)*

A low level input on this pin will initiate an interrupt request sequence provided the mask bit (I) in the CC is clear. Since IRQ stacks the entire machine state, it provides a slower response to interrupts than FIRQ. IRQ also has a lower priority than FIRQ. Again, the interrupt service routine should clear the source of the interrupt before doing an RTI. See Figure 9.

*NMI, FIRQ, and IRQ requests are sampled on the falling edge of Q. One cycle is required for synchronization before these interrupts are reci nized. The pending interruptish will not be serviced until completion of the current instruction unless a SYNC or CWAI condition is present. If IRQ and FIRQ do not remain low until completion of the current instruction they may not be recognized. However, NMI is latched and need only rel<u>ain l</u>ow for one cycle. No interrupts are recognized or latched between the falling edge of RESET and the rising edge of BS indicating RESET acknowledge.

MOTOROLA MICROPROCESSOR DATA

MOTOROLA MICROPROCESSOR DATA

3-1372

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MC6809

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3-1373

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MC6809

XTAL, EXTAL

These inputs are used to connect the on-chip oscillator to an external parallel-resonant crystal. Alternately, the pin EXTAL may be used as a TTL level input for external timing by grounding XTAL. The crystal or external frequency is four times the bus frequency. See Figure 7. Proper RF layout techniques should be observed in the layout of printed circuit boards.

E. Q.

E is similar to the MC6800 bus timing signal phase 2; Q is a quadrature clock signal which leads E. Q has no parrallel on the MC6800. Addresses from the MPU will be valid with the leading edge of Q. Data is latched on the falling edge of E. Timing for E and Q is shown in Figure 11.

MRDY

This input control signal allows stretching of E and Q to extend data-access time. E and Q operate normally while MRDY is high. When MRDY is low, E and Q may be stretched in integral multiples of quarter (%) bus cycles, thus allowing interface to slow memories, as shown in Figure 12(a). During non-valid memory access (VMA cycles), MRDY has no effect on stretching E and Q; this inhibits slowing the processor during "don't care" bus accesses. MRDY may also be used to stretch clocks (for slow memory) when bus control has been transferred to an external device (through the use of HALT and DMA/BREQ).

DMA/BREQ

The DMA/BREQ input provides a method of suspending execution and acquiring the MPU bus for another use, as shown in Figure 13. Typical uses include DMA and dynamic memory refresh.

A low level on this pin will stop instruction execution at the end of the current cycle unless pre-empted by self-refresh. The MPU will acknowledge DMA/BREQ by setting BA and BS to a one. The requesting device will now have up to 15 bus cycles before the MPU retrieves the bus for self-refresh. Self-refresh requires one bus cycle with a leading and trailing dead cycle. See Figure 14. The self-refresh counter is only cleared if DMA/BREQ is inactive for two or more MPU cycles

Typically, the DMA controller will request to use the bus by asserting DMA/BREQ pin low on the leading edge of E. When the MPU replies by setting BA and BS to a one, that cycle will be a dead cycle used to transfer bus mastership to the DMA controller

False memory accesses may be prevented during any dead cycles by developing a system DMAVMA signal which is LOW in any cycle when BA has changed.

When BA goes low (either as a result of DMA BREQ HIGH or MPU self-refresh), the DMA device should be taken off the bus. Another dead cycle will elapse before the MPU accesses memory to allow transfer of bus mastership without contention

MPU OPERATION

During normal operation, the MPU fetches an instruction from memory and then executes the requested function. This sequence begins after RESET and is repeated indefinitely unless altered by a special instruction or hardware occurrence. Software instructions that alter normal MPU operation are: SWI, SWI2, SWI3, CWAI, RTI, and SYNC. An interrupt, HALT. or DMA BREQ can also alter the normal execution of instructions. Figure 15 is the flowchart for the MC6809.

FIGURE 11 - E/O RELATIONSHIP

NOTE: Waveform measurements for all inputs and outputs are specified at logic high 2.0 V and logic low 0.8 V unless otherwise specified

MOTOROLA MICROPROCESSOR DATA

FIGURE 12 - MRDY TIMING AND SYNCHRONIZATION

(a) Timing

(b) Synchronization

MOTOROLA MICROPROCESSOR DATA

3-1375

FIGURE 14 - AUTO-REFRESH DMA TIMING (>14 CYCLES) (REVERSE CYCLE STEALING)

* DMAVMA is a signal which is developed externally, but is a system requirement for DMA. Refer to Application Note AN-820.

NOTE: Waveform measurements for all inputs and outputs are specified at logic high 2.0 V and logic low 0.8 V unless otherwise specified.

MOTOROLA MICROPROCESSOR DATA 3-1376

MOTOROLA MICROPROCESSOR DATA

3-1377

ADDRESSING MODES

The basic instructions of any computer are greatly enhanced by the presence of powerful addressing modes. The MC6809 has the most complete set of addressing modes available on any microcomputer. For example, the MC6809 has 59 basic instructions; however, it recognizes 1464 different variations of instructions and addressing modes. The addressing modes support modern programming techniques. The following addressing modes are available on the MC6809:

Inherent (Includes Accumulator) Immediate Extended **Extended Indirect** Direct Register Indexed Zero-Offset **Constant Offset Accumulator Offset** Auto Increment/Decrement

Indexed Indirect

Relative

Short/Long Relative Branching Program Counter Relative Addressing

INHERENT (INCLUDES ACCUMULATOR)

In this addressing mode, the opcode of the instruction contains all the address information necessary. Examples of inherent addressing are: ABX, DAA, SWI, ASRA, and CLRB.

IMMEDIATE ADDRESSING

In immediate addressing, the effective address of the data is the location immediately following the opcode (i.e., the data to be used in the instruction immediately following the opcode of the instruction). The MC6809 uses both 8- and 16-bit immediate values depending on the size of argument specified by the opcode. Examples of instructions with immediate addressing are:

LDA #\$20

- LDX #\$F000
- LDY #CAT

NOTE

signifies immediate addressing; \$ signifies hexadecimal value.

EXTENDED ADDRESSING

In extended addressing, the contents of the two bytes immediately following the opcode fully specify the 16-bit effective address used by the instruction. Note that the address generated by an extended instruction defines an absolute address and is not position independent. Examples of extended addressing include:

LDD **52000**

EXTENDED INDIRECT - As in the special case of indexed addressing (discussed below), one level of indirection may be added to extended addressing. In extended indirect, the two bytes following the postbyte of an indexed instruction contain the address of the data.

DIRECT ADDRESSING

Direct addressing is similar to extended addressing except that only one byte of address follows the opcode. This byte specifies the lower eight bits of the address to be used. The upper eight bits of the address are supplied by the direct page register. Since only one byte of address is required in direct addressing, this mode requires less memory and executes faster than extended addressing. Of course, only 256 locations (one page) can be accessed without redefining the contents of the DP register. Since the DP register is set to \$00 on reset, direct addressing on the MC6809 is compatible with direct addressing on the M6800. Indirection is not allowed in direct addressing. Some examples of direct addressing are:

> LDA \$30 SETDP \$10 (assembler directive) LDB \$1030 $<$ CAT LDD.

NOTF

< is an assembler directive which forces direct addressing.

REGISTER ADDRESSING

Some opcodes are followed by a byte that defines a register or set of registers to be used by the instruction. This is called a postbyte. Some examples of register addressing are

INDEXED ADDRESSING

In all indexed addressing, one of the pointer registers (X, Y, U, S, and sometimes PC) is used in a calculation of the effective address of the operand to be used by the instruction. Five basic types of indexing are available and are discussed below. The postbyte of an indexed instruction specifies the basic type and variation of the addressing mode as well as the pointer register to be used. Figure 16 lists the legal formats for the postbyte. Table 2 gives the assembler form and the number of cycles and bytes added to the basic values for indexed addressing for each variation.

MOTOROLA MICROPROCESSOR DATA

FIGURE 16 - INDEXED ADDRESSING POSTBYTE REGISTER BIT ASSIGNMENTS

ZERO-OFFSET INDEXED - In this mode, the selected pointer register contains the effective address of the data to be used by the instruction. This is the fastest indexing mode.

Examples are:

LDD 0, X

LDA .S

CONSTANT OFFSET INDEXED - In this mode, a two's-complement offset and the contents of one of the pointer registers are added to form the effective address of the operand. The pointer register's initial content is unchanged by the addition. Three sizes of offset are available:

5-bit (-16 to -15)

8-bit (-128 to -128)

16-bit (-32768 to +32767)

The twos complement 5-bit offset is included in the postbyte and, therefore, is most efficient in use of bytes and cycles. The twos complement 8-bit offset is contained in a single byte following the postbyte. The twos complement 16-bit offset is in the two bytes following the postbyte. In most cases the programmer need not be cocerned with the size of this offset since the assembler will select the optimal size automatically. Examples of constant-offset indexing are:

 LDA 23, X $LDX -2,S$ LDY 300,X LDU CAT,Y

TABLE 2 - INDEXED ADDRESSING MODE

 $R = X$, Y, U, or S $x = Don't Care$

 $00 = X$ $01 = Y$

 $10 = U$

 $11 = S$

 $\frac{+}{+}$ and $\frac{+}{+}$ indicate the number of additional cycles and bytes for the particular variation.

MOTOROLA MICROPROCESSOR DATA

3-1379

ACCUMULATOR-OFFSET INDEXED - This mode is similar to constant offset indexed except that the twoscomplement value in one of the accumulators (A, B, or D) and the contents of one of the pointer registers are added to form the effective address of the operand. The contents of both the accumulator and the pointer register are unchanged by the addition. The postbyte specifies which accumulator to use as an offset and no additional bytes are required. The advantage of an accumulator offset is that the value of the offset can be calculated by a program at run-time.

Some examples are: LDA B, Y

LDX D.Y LEAX B, X

AUTO INCREMENT/DECREMENT INDEXED - In the auto increment addressing mode, the pointer register contains the address of the operand. Then, after the pointer register is used it is incremented by one or two. This addressing mode is useful in stepping through tables, moving data, or for the creation of software stacks. In auto decrement, the pointer register is decremented prior to use as the address of the data. The use of auto decrement is similar to that of auto increment; but the tables, etc., are scanned from the high to low addresses. i The size of the increment/decrement can be either one or two to allow for tables of either 8- or 16-bit data to be accessed and is selectable by the programmer. The pre-decrement, post-increment nature of these modes allows them to be used to create additional software stacks that behave identically to the U and S stacks.

Some examples of the auto increment/decrement addressing modes are:

Care should be taken in performing operations on 16-bit pointer registers (X, Y, U, S) where the same register is used to calculate the effective address.

Consider the following instruction:

STX $0, X + + (X)$ initialized to 0)

The desired result is to store zero in locations \$0000 and \$0001, then increment X to point to \$0002. In reality, the following occurs:

INDEXED INDIRECT - All of the indexing modes, with the exception of auto increment/decrement by one or a $±$ 4-bit offset, may have an additional level of indirection specified. In indirect addressing, the effective address is contained at the location specified by the contents of the index register plus any offset. In the example below, the A accumulator is loaded indirectly using an effective address calculated from the index register and an offset.

nt those which are meaningless (e.g., auto increment/decrement by one indirect). Some examples of indexed indirect are:

IDA $f.X$ LDD $[10.5]$ **IDA** $[B,Y]$ חח ו $[.X + +]$

RELATIVE ADDRESSING

The byte(s) following the branch opcode is (are) treated as a signed offset which may be added to the program counter. If the branch condition is true, then the calculated address (PC + signed offset) is loaded into the program counter. Program execution continues at the new location as indicated by the PC; short (one byte offset) and long (two bytes offset) relative addressing modes are available. All of memory can be reached in long relative addressing as an effective address is interpreted modulo 216. Some examples of relative addressing are:

PROGRAM COUNTER RELATIVE - The PC can be used as the pointer register with 8- or 16-bit signed offsets. As in relative addressing, the offset is added to the current PC to create the effective address. The effective address is then used as the address of the operand or data. Program counter relative addressing is used for writing position independent programs. Tables related to a particular routine will maintain the same relationship after the routine is moved, if referenced relative to the program counter. Examples are:

Since program counter relative is a type of indexing, an additional level of indirection is available.

MOTOROLA MICROPROCESSOR DATA

3-1380

INSTRUCTION SET

The instruction set of the MC6809 is similar to that of the MC6800 and is upward compatible at the source code level. The number of opcodes has been reduced from 72 to 59, but because of the expanded architecture and additional addressing modes, the number of available opcodes (with different addressing modes) has risen from 197 to 1464.

Some of the new instructions are described in detail below.

PSHU/PSHS

The push instructions have the capability of pushing onto either the hardware stack (S) or user stack (U) any single register or set of registers with a single instruction.

PULU/PULS

The pull instructions have the same capability of the push instruction, in reverse order. The byte immediately following the push or pull opcode determines which register or registers are to be pushed or pulled. The actual push/pull sequence is fixed; each bit defines a unique register to push or pull, as shown below.

TFR/FXG

Within the MC6809, any register may be transferred to or exchanged with another or like size, i.e., 8 bit to 8 bit or 16 bit to 16 bit. Bits 4-7 of post byte define the source register, while bits 0-3 represent the destination register. These are denoted as follows:

All other combinations are undefined and INVALID.

I FAX/LEAV/LEAU/LEAS

The LEA (load effective address) works by calculating the effective address used in an indexed instruction and stores that address value, rather than the data at that address, in a pointer register. This makes all the features of the internal addressing hardware available to the programmer. Some of the implications of this instruction are illustrated in Table 3. The LEA instruction also allows the user to access data

and tables in a position independent manner. For example:

This sample program prints: 'MESSAGE'. By writing MSG1, PCR, the assembler computes the distance between the present address and MSG1. This result is placed as a constant into the LEAX instruction which will be indexed from the PC value at the time of execution. No matter where the code is located when it is executed, the computed offset from the PC will put the absolute address of MSG1 into the X pointer register. This code is totally position independent.

The LEA instructions are very powerful and use an internal holding register (temp). Care must be exercised when using the LEA instructions with the auto increment and auto decrement addressing modes due to the sequence of internal operations. The LEA internal sequence is outlined as follows: (any of the 16-bit pointer registers X, Y, $LEAa.b+$

$LEAa$, - b

MSG1

- (calculate EA with predecrement) 1. $b-1 \rightarrow temp$
- 2. $b-1 \rightarrow b$ (modify b. predecrement)
- (load a) 3. temp \rightarrow a

TABLE 3 - LEA EXAMPLES

MOTOROLA MICROPROCESSOR DATA

Auto increment-by-two and auto decrement-by-two instructions work similarly. Note that LEAX, X+ does not change X; however, LEAX, - X does decrement; LEAX 1, X should be used to increment X by one.

MUL

Multiplies the unsigned binary numbers in the A and B accumulator and places the unsigned result into the 16-bit D accumulator. The unsigned multiply also allows multipleprecision multiplications.

LONG AND SHORT RELATIVE BRANCHES

The MC6809 has the capability of program counter relative branching throughout the entire memory map. In this mode, if the branch is to be taken, the 8- or 16-bit signed offset is added to the value of the program counter to be used as the effective address. This allows the program to branch anywhere in the 64K memory map. Position-independent code can be easily generated through the use of relative branching. Both short (8-bit) and long (16-bit) branches are available.

SYNC

After encountering a sync instruction, the MPU enters a sync state, stops processing instructions, and waits for an interrupt. If the pending interrupt is non-maskable (NMI) or maskable (FIRQ, IRQ) with its mask bit (F or I) clear, the processor will clear the sync state and perform the normal interrupt stacking and service routine. Since FIRO and IRO are not edge-triggered, a low level with a minimum duration of three bus cycles is required to assure that the interrupt will be taken. If the pending interrupt is maskable (FIRO, IRO) with its mask bit (F or I) set, the processor will clear the sync state and continue processing by executing the next in-line instruction. Figure 18 depicts sync timing.

SOFTWARE INTERRUPTS

A software interrupt is an instruction which will cause an interrupt and its associated vector fetch. These software interrupts are useful in operating system calls, software debugging, trace operations, memory mapping, and software development systems. Three levels of SWI are available on the MC6809, and are prioritized in the following order: SWI, SWI2, SWI3.

16-BIT OPERATION

The MC6809 has the capability of processing 16-bit data. These instructions include loads, stores, compares, adds, subtracts, transfers, exchanges, pushes, and pulls.

CYCLE-BY-CYCLE OPERATION

The address bus cycle-by-cycle performance chart (Figure 18) illustrates the memory-access sequence corresponding to each possible instruction and addressing mode in the MC6809. Each instruction begins with an opcode fetch. While that opcode is being internally decoded, the next program byte is always fetched. (Most instructions will use the next byte, so this technique considerably speeds throughput.) Next, the operation of each opcode will follow the flowchart. VMA is an indication of FFFF₁₆ on the address bus, R/\overline{W} = 1 and $BS = 0$. The following examples illustrate the use of the chart.

 \sim 1.4. 1.500 (0.4. \pm 1.5. \pm

CYCLE-BY-CYCLE FLOW

Example 2: DEC (Extended)

CYCLE-BY-CYCLE FLOW

* The data bus has the data at that particular address

INSTRUCTION SET TABLES

The instructions of the MC6809 have been broken down into five different categories. They are as follows:

- 8-bit operation (Table 4)
- 16-bit operation (Table 5)

Index register/stack pointer instructions (Table 6)

- Relative branches (long or short) (Table 7)
	- Miscellaneous instructions (Table 8)

Hexadecimal values for the instructions are given in Table 9

PROGRAMMING AID

Figure 19 contains a compilation of data that will assist in programming the MC6809.

MOTOROLA MICROPROCESSOR DATA

3-1382

- NOTES:
1. If the associated mask bit is set when the interrupt is requested, this cycle will be an instruction fetch from address location PC + 1. However, if the in-
1. If the associated mask bit is set when the interru
- 3. Waveform measurements for all inputs and outputs are specified at logic high 2.0 V and logic low 0.8 V unless otherwise specified the processor out of SYNC.

MOTOROLA MICROPROCESSOR DATA

3-1383

FIGURE 18 - CYCLE-BY-CYCLE PERFORMANCE (Sheet 1 of 5)

MOTOROLA MICROPROCESSOR DATA

3-1384

FIGURE 18 - CYCLE-BY-CYCLE PERFORMANCE (Sheet 2 of 5)

MOTOROLA MICROPROCESSOR DATA

3-1385

FIGURE 18 - CYCLE-BY-CYCLE PERFORMANCE (Sheet 3 of 5)

MOTOROLA MICROPROCESSOR DATA

3-1386

FIGURE 18 - CYCLE-BY-CYCLE PERFORMANCE (Sheet 4 of 5)

MOTOROLA MICROPROCESSOR DATA

3-1387

FIGURE 18 - CYCLE-BY-CYCLE PERFORMANCE (Sheet 5 of 5)

3-1388

TABLE 4 - 8-BIT ACCUMULATOR AND MEMORY INSTRUCTIONS

NOTE: A, B, CC, or DP may be pushed to (pulled from) stack with either PSHS, PSHU (PULS, PULU) instructions.

TABLE 5 - 16-BIT ACCUMULATOR AND MEMORY INSTRUCTIONS

NOTE: D may be pushed (pulled) to stack with either PSHS, PSHU (PULS, PULU) instructions.

MOTOROLA MICROPROCESSOR DATA

TABLE 6 - INDEX REGISTER/STACK POINTER INSTRUCTIONS

Instruction	Description
CMPS, CMPU	Compare memory from stack pointer
CMPX, CMPY	Compare memory from index register
EXG R1, R2	Exchange D, X, Y, X, U, or PC with D, X Y, S, U, or PC
LEAS, LEAU	Load effective address into stack pointer
LEAX. LEAY	Load effective address into index register
LDS, LDU	Load stack pointer from memory
LDX, LDY	Load index register from memory
PSHS	Push A, B, CC, DP, D, X, Y, U, or PC onto hardware stack
PSHU	Push A, B, CC, DP, D, X, Y, S, or PC onto user stack
PULS	Pull A, B, CC, DP, D, X, Y, U, or PC from hardware stack
PULU	Pull A, B, CC, DP, D, X, Y, S, or PC from hardware stack
STS, STU	Store stack pointer to memory
STX, STY	Store index register to memory
TFR R1, R2	Transfer D, X, Y, S, U or PC to D, X, Y, S, U, or PC
ABX	Add B accumulator to X (unsigned)

TABLE 7 - BRANCH INSTRUCTIONS

TABLE 8 - MISCELLANEOUS INSTRUCTIONS

MOTOROLA MICROPROCESSOR DATA

3-1390

TABLE 9 - HEXADECIMAL VALUES OF MACHINE CODES

LEGEND:

 \sim Number of MPU cycles (less possible push pull or indexed-mode cycles)

Number of program bytes

* Denotes unused opcode

MOTOROLA MICROPROCESSOR DATA

MOTOROLA MICROPROCESSOR DATA

3-1392

FIGURE 19 - PROGRAMMING AID

- Arithmetic Minus

· Multiply

Z Zero result

-
- V Overflow, 2's complement
- C Carry from ALU
-
- V Logical or
- A Logical and
- ↓ Logical Exclusive or

MOTOROLA MICROPROCESSOR DATA

3-1393

FIGURE 19 - PROGRAMMING AID (CONTINUED)

NOTES:

1. This column gives a base cycle and byte count. To obtain total count, add the values obtained from the INDEXED ADDRESSING MODE table, Table 2.

2. R1 and R2 may be any pair of 8 bit or any pair of 16 bit registers.

The 8 bit registers are: A, B, CC, DP

The 16 bit registers are: X, Y, U, S, D, PC

3. EA is the effective address.

4. The PSH and PUL instructions require 5 cycles plus 1 cycle for each byte pushed or pulled.

5. 5(6) means: 5 cycles if branch not taken, 6 cycles if taken (Branch instructions).

6. SWI sets I and F bits. SWI2 and SWI3 do not affect I and F.

7. Conditions Codes set as a direct result of the instruction.

8. Vaue of half-carry flag is undefined.

9. Special Case - Carry set if b7 is SET.

MOTOROLA MICROPROCESSOR DATA

3-1394

FIGURE 19 - PROGRAMMING AID (CONTINUED)

Branch Instructions

SIMPLE BRANCHES

SIMPLE CONDITIONAL BRANCHES (Notes 1-4)

OP

False

True

Test

NOTES:

1. All conditional branches have both short and long variations.

2. All short branches are two bytes and require three cycles.

3. All conditional long branches are formed by prefixing the short branch opcode with \$10 and using a 16-bit destination offset.

4. All conditional long branches require four bytes and six cycles if the branch is taken or five cycles if the branch is not taken.

MOTOROLA MICROPROCESSOR DATA

3-1395

ORDERING INFORMATION

PIN ASSIGNMENT

MOTOROLA MICROPROCESSOR DATA

3-1396